PROCESS GUIDE

Rapid Z[®] Galvanized Welding



*As compared to DCEN with E70C-GS on galvanized steel.

Overview

Rapid Z[®] – High Speed, Low Porosity.

- Less Spatter*
- Better Bead Appearance*
- Less Internal & External Porosity*
- Higher Productivity & Less Rework*

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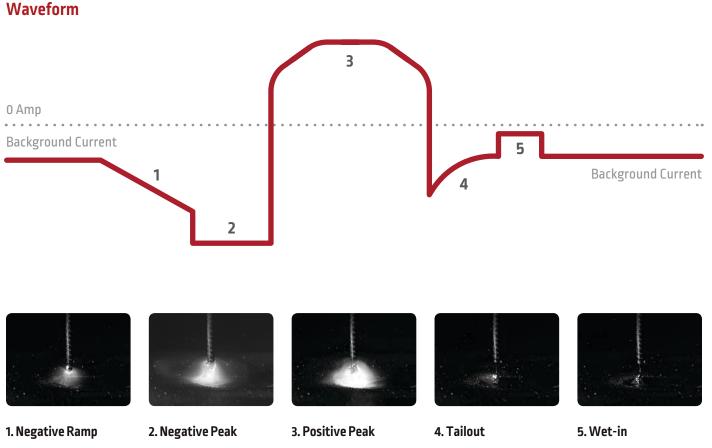


Process Description

When it comes to making automotive parts, productivity and quality are the highest priorities. But those targets can be hard to hit when welding galvanized material with conventional processes. Welding on galvanized can be difficult for many reasons. The zinc coating thickness varies, part fit up varies, and porosity is likely, forcing a difficult balance between proper weld size, faster weld speed, or good x-ray quality.

Process Z[™] provides all three, without compromising. Metalshield[®] Z gas-shielded wire, combined with Rapid Z[®] waveform technology operating on AC polarity, minimizes the internal porosity of welds and assures virtually no external porosity while maintaining faster travel speeds.

With the Rapid Z waveform the electrode droplet transfer is focused and predictable. Less of the surrounding zinc coating is introduced into the weld – meaning less internal porosity. Smooth droplet transfer also delivers more stability and less spatter when welding at increased travel speeds.



Ramps current slowly to avoid spatter from a superheated molten droplet.

Provides energy

to create a molten droplet without transferring.

Provides a pinch force to the droplet.

Reduced current relaxes the plasma force as the droplet approaches the puddle.

Proprietary hardware quickly reduces the current at the instant the droplet contacts the puddle, reducing spatter as the droplet detaches.

Synergic Welding

 Adjust WFS to the desired setting. Refer to the Applications section for the recommended settings.



Voltage and UltimArc[®]

- 2. Based on WFS, a pre-programmed nominal voltage is selected.
- 3. Adjusting voltage increases or decreases the arc length, allowing the user to fine tune arc characteristics.
- 4. Synergic Weld modes improve the ease of set-up by pre-selecting an ideal voltage based on the selected WFS. The user can then fine tune their Voltage setting based on their personal preference and can easily see whether they are above or below the nominal setting.
- **5.** The UltimArc[®] control fine-tunes the heat input into the plate.



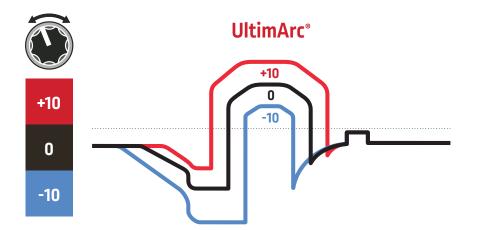
Voltage Display

Above Ideal Voltage (Upper bar displayed)

At Ideal Voltage (No bar displayed)

Below Ideal Voltage (Lower bar displayed)





ASTM Designations for Hot-Dipped Galvanized Plate

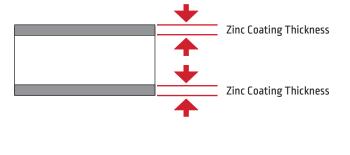
ENGLISH:

60G60G designates the minimum coating weight per ASTM specification.

METRIC:

Z120 designates the minimum coating weight per ASTM specification.

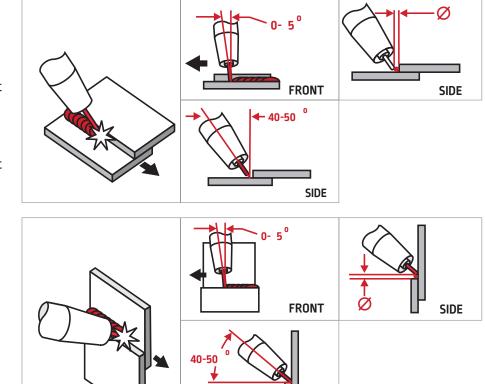
Typical Zinc Coating Thickness for these ASTM specifications average 9.1 microns.



Synergic Procedures – 2F Lap Joint

- Use a 0-5° drag angle.
- Use a 40-50° work angle.
- For 2F-Horizontal, position the electrode approximately one electrode diameter outside the joint favoring the bottom leg.
- For 2F-Vertical, position the electrode approximately one electrode diameter outside the joint favoring the top leg.

Synergic Procedures – 2F Lap Joint continued on page 4

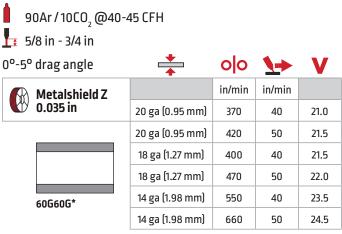


SIDE

See Customer Assistance Policy and Disclaimer Notice on page 9.

Synergic Procedures – 2F Lap Joint (continued)

ENGLISH

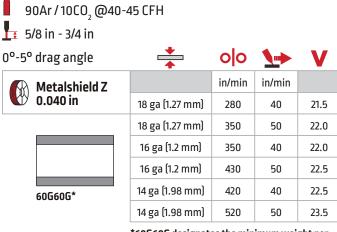


*60G60G designates the minimum weight per ASTM specification

METRIC

80Ar / 20CO ₂ @40-45 l/min 1 6 mm - 19 mm					
0°-5° drag angle	*	00		V	
Metalshield Z	mm	m/min	cm/min		
🖤 0.9 mm	1.0	9.4	100	21.0	
	1.0	10.7	125	21.5	
	1.2	10.2	100	21.5	
	1.2	11.9	125	22.0	
Z120**	2.0	14.0	100	23.5	
	2.0	16.8	125	24.5	
		gnates the ecification	ninimum we	eight per	

ENGLISH



*60G60G designates the minimum weight per ASTM specification

METRIC

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80Ar / 20CO ₂ @40-45 l/min						
16 mm - 19 mm						
0°-5° drag angle	*	00		V		
Metalshield Z	mm	m/min	cm/min			
🖤 1.0 mm	1.2	7.1	100	21.5		
	1.2	8.9	125	22.0		
	1.5	8.9	100	22.0		
Z120**	1.5	10.9	125	22.5		
	2.0	10.7	100	22.5		
	2.0	13.2	125	23.5		

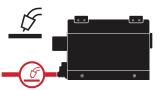
**Z120 designates the minimum weight per ASTM specification

See Customer Assistance Policy and Disclaimer Notice on page 10.

Sense Leads

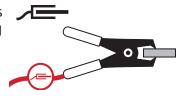
An electrode sense lead is required. This is a standard connection in an ArcLink[®] cable.

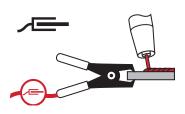
DO <u>NOT</u> connect either sense lead to a welding stud on the power source as this may result in erratic arc behavior.



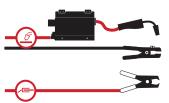
A work sense lead (optional) is highly recommended for total welding cable lengths >50 ft. and should be connected directly to the workpiece.

For best performance, connect the work sense lead close to the welding arc.





The work sense lead should be separated away from welding cables to minimize interference.



DO <u>NOT</u> route sense lead cable close to high current welding cables as this may distort the sense lead signal.

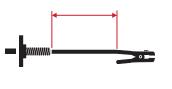


Work Leads

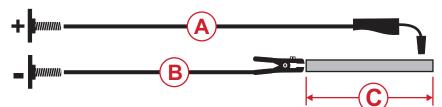
Connect the work lead to the negative stud on the power source and directly to the workpiece. Maintain the shortest connection length possible.

The total length of the welding current loop (A+B+C) should be minimized to reduce inductance. Route cables (A,B) close together to further reduce cable inductance.

For configurations with excessive inductance, use Lincoln Electric[®] patented coaxial welding cables.



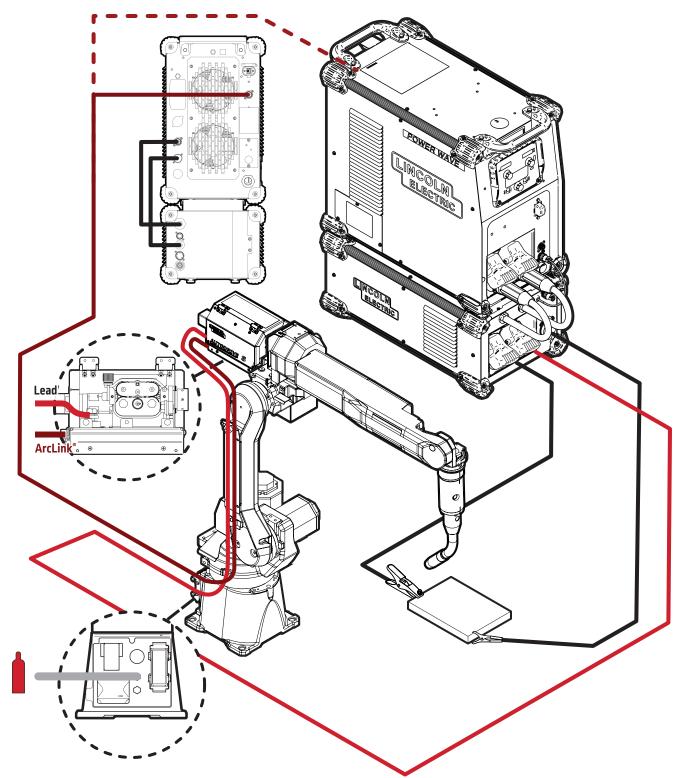
Test cable inductance levels using the Power Wave® Manager software exclusively from Lincoln Electric® Software. Available at www.powerwavesoftware.com.





Lincoln Electric[®] coaxial cables combine the positive and negative welding leads into one cable to minimize cable inductance.



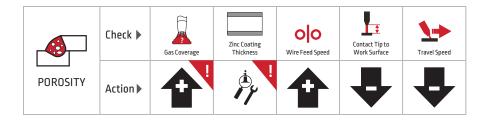


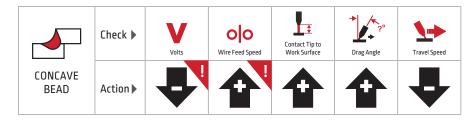
Connection Diagram – Advanced Module

Troubleshooting



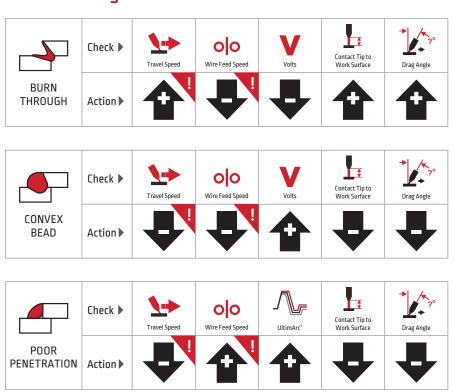






	Check 🕨	Volts	Travel Speed	OO Wire Feed Speed
UNDER CUT	Action			₽





Troubleshooting



lcons

Wire Type	Gas	Material Thickness	O O Wire Feed Speed	Travel Speed	Volts	A Amps	Contact Tip to Work Surface	Drag Angle	Arc Length
Lontrol Knob	Weld Stud	Torch	Work Sense Lead	Work Clamp	Torch Nozzle	Spatter	Erratic Arc	Proper Feeding	Stop / Avoid
Knurled Drive Rolls	Gas Coverage	Zinc Coating Thickness	Porosity	Concave Bead	Burn Through	Under Cut	Convex Bead	Poor Penetration	UltimArc*

Technical Terms

Cable Inductance	Resistance to change in current.
GMAW	Gas metal arc welding including metal inert gas (MIG) and metal active gas (MAG) welding.
Porosity	Gas entrapped in solidifying metal forms spherical or elongated pores in the weld.
Drag Angle	The angle at which the electrode trails the weld pool relative to the direction of travel.
Synergic	A mode of control which automatically selects a pre-programmed nominal voltage based on the wire feed speed (WFS) set by the operator.
Work Angle	The angle of the electrode, off perpendicular, relative to the work piece surface.
Zinc Coating Thickness	Thickness of Zinc Coating; typically designated by weight per ASTM specification.

Procedure Notes

All listed procedures are starting points and may require some adjustment depending on the specific application.

Torch angle, electrode placement, contamination, mill scale, joint fit up, and joint consistency are factors that may require special consideration depending on the specific application.

At higher travel speeds, joint fit up, wire placement, and contamination all become factors that are more significant.

The result of welding at higher travel speeds is a tendency to produce more spatter, less penetration, more undercut, and a less desirable bead shape. Depending on the limitations / requirements of the actual application, slower travel speeds and higher arc voltages may be required.

As the travel speed increases in fast follow applications (1/4" to 14 Gauge), a tighter arc length must be maintained so that the puddle properly follows the arc. Operators typically reduce the arc length control (Voltage) to achieve this. At faster travel speeds, the bead-shape can become very convex (or ropy), and the weld will not "wet" well. There is a point at which the arc is set so short that the arc will become unstable and stubbing will occur. This forms a limitation of just how fast the travel speed can be raised.

It is ultimately the responsibility of the end user to ensure the proper weld deposition rate, bead profile, and structural integrity of a given weld application.

CUSTOMER ASSISTANCE POLICY

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