AC Aluminum Pulse (GMAW) Weld Process Guide

Overview

AC Aluminum Pulse for superior quality welding*.

- Increases travel speed up to 40%
- Increases deposition up to 75%
- Decreases burnthrough
- Improves gap bridging

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*Based on a side by side comparison of AC Aluminum Pulse and Pulse.



AC Aluminum Pulse Details

Process Description

AC Aluminum Pulse (GMAW) brings features that cannot be realized with standard DC pulse MIG welding. The AC pulse process reduces the heat input by focusing the energy away from the base plate and switching the polarity of the arc.

Productivity increases with improved deposition rates using **AC Aluminum Pulse** (GMAW) waveform technology are available exclusively on the Power Wave[®] Advanced Module. This is possible because the **negative polarity** arc redirects the heat away from the workpiece, reducing the chance of burnthrough. The UltimArc[™] and synergic precision controls give the user full control over heat input, penetration while improving cleaning action, and allowing for faster travel speeds on thin material.

With this technology, it is now easier to weld thin aluminum and bridge gaps. Precise control of the heat input is achieved with the UltimArc[™] control using **AC Aluminum Pulse** (GMAW). UltimArc[™] adjusts the amount of DC negative time during the background to allow less heat to be transferred to the workpiece.







AC Aluminum Pulse Optimization

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Synergic Welding



AC Aluminum Pulse waveforms are synergic weld modes. Based on the wire feed speed **1**, set by the operator, a pre-programmed voltage is automatically selected **2**. Fine tune the arc length using Voltage adjustment **3**.



Adjust WFS to the desired setting. Refer to the Application section for the recommended settings.

Based on WFS a preprogrammed nominal voltage is selected.

Adjusting voltage increases or decreases the arc length, allowing the user to fine tune arc characteristics.

A note on Trim.

Lincoln Electric[®] developed Trim as a means to simplify the complexities of Arc Length control in advanced welding application set-up, such as Pulse. Now, Lincoln Electric[®] Synergic Weld modes improve the ease of set-up by preselecting an ideal voltage based on the selected WFS. The user can then fine tune their Voltage setting based on their personal preference and can easily see whether they are above or below the nominal setting.

UltimArc[™] Control

The **UltimArc**[™] control fine tunes the heat input into the plate.

Increasing (+) the setting provides more heat into the weld puddle resulting in a more focused arc.

Decreasing(-) the setting reduces heat directed into the puddle resulting in a less focused arc.









1F / PA Lap Automatic



- Use a 0-10° push angle.
- Use a 35° work angle.

• Position the electrode approximately one electrode diameter outside the joint favoring the bottom leg.

• For less than 2mm applications position the electrode directly in the joint or slightly favoring the top edge. May require decreased work angle.

100Ar		ala			*	Λ-		
1 /2 in.	•	00		Α	V	UltimArc™		
SuperGlaze [®] 4043	mm (ga)	in/min	in/min					
🖤 0.035" (0.9mm)	2.5 (12)	450	35	116	19.0 - 21.0	2.5		
	2.0 (14)	375	35	99	18.5 - 20.5	0.0		
	1.5 (16)	340	35	91	17.7 - 19.7	0.0		
	1.0 (19)	195	20	62	16.7 - 18.7	-2.5		
SuperGlaze [®] 4043	3.0 (11)	400	40	181	19.0 - 21.0	5.0		
3/64" (1.2mm)	2.0 (14)	280	40	132	18.1 - 20.1	0.0		
	1.5 (16)	200	35	100	17.0 - 19.0	0.0		
	1.0 (19)	120	25	75	16.5 - 18.5	0.0		
SuperGlaze [®] 4043	3.0 (11)	215	40	188	18.8 - 20.8	0.0		
SuperGlaze [®] 4043 1/16" (1.6mm)	2.0 (14)	140	40	132	18.1 - 20.1	-3.0		
	1.5 (16)	110	35	113	17.4 - 19.4	-10.0		
SuperGlaze [®] 5356	2.5 (12)	675	40	145	18.8 - 20.8	10.0		
0.035" (0.9mm)	2.0 (14)	550	40	120	17.8 - 19.8	5.0		
	1.5 (16)	425	30	96	16.4 - 18.4	0.0		
	1.0 (19)	200	20	54	14.9 - 16.9	-5.0		
SuperGlaze [®] 5356	3.0 (11)	550	45	212	20.0 - 22.0	5.0		
3/64" (1.2mm)	2.5 (12)	425	45	159	17.8 - 19.8	0.0		
	2.0 (14)	320	45	132	17.3 - 19.3	0.0		
	1.5 (16)	275	40	116	16.3 - 18.3	0.0		
	1.0 (19)	125	25	68	15.3 - 17.3	0.0		
SuperGlaze [®] 5356	3.0 (11)	350	40	234	19.2 - 21.2	10.0		
1/16" (1.6mm)	2.0 (14)	175	40	134	16.4 - 18.4	2.5		
	1.5 (16)	140	35	109	16.0 - 18.0	-5.0		
	1.0 (19)	100	35	86	15.3 - 17.3	-10.0		
	* Optimal voltage may vary based on cable and torch configuration.							



1F / PA Lap Semi-Automatic



- Use a 0-10° push angle.
- Use a 35° work angle.

• Position the electrode approximately one electrode diameter outside the joint favoring the bottom leg.

• For less than 2mm applications position the electrode directly in the joint or slightly favoring the top edge. May require decreased work angle.

100Ar ↓ 1/2 in.	★	၀၀	Α	V*	UltimArc™
SuperGlaze [®] 4043 0.035" (0.9mm)	mm (ga)	in/min			
0.035" (0.9mm)	2.5 (12)	465	110	20.4 - 22.4	0.0
	2.0 (14)	390	100	19.5 - 21.5	0.0
	1.5 (16)	300	83	19.0 - 21.0	0.0
	1.0 (19)	155	56	17.5 - 19.5	-5.0
SuperGlaze [®] 4043	3.0 (11)	300	140	20.5 - 22.5	0.0
SuperGlaze [®] 4043 3/64" (1.2mm)	2.0 (14)	210	105	19.2 - 21.2	0.0
	1.5 (16)	175	95	18.7 - 20.7	0.0
	1.0 (19)	110	70	17.9 - 19.9	-5.0
SuperGlaze [®] 4043 1/16" (1.6mm)	3.0 (11)	150	149	20.5 - 22.5	0.0
🛛 🖤 1/16" (1.6mm)	2.0 (14)	115	129	20.0 - 22.0	-5.0
SuperGlaze [®] 5356 0.035" (0.9mm)	2.5 (12)	525	118	18.4 - 20.4	5.0
0.035" (0.9mm)	2.0 (14)	460	107	18.1 - 20.1	2.5
	1.5 (16)	365	91	17.2 - 19.2	0.0
	1.0 (19)	200	58	16.3 - 18.3	-5.0
SuperGlaze [®] 5356 3/64" (1.2mm)	3.0 (11)	400	154	18.5 - 20.5	5.0
🛛 🖤 3/64" (1.2mm)	2.0 (14)	275	118	17.9 - 19.9	0.0
	1.5 (16)	210	95	16.7 - 18.7	0.0
	1.0 (19)	120	64	15.3 - 17.3	-5.0
L					
SuperGlaze [®] 5356 1/16" (1.6mm)	3.0 (11)	245	171	19.6 - 21.6	0.0
1/16" (1.6mm)	2.0 (14)	125	107	16.9 - 18.9	0.0
	1.5 (16)	100	88	16.7 - 18.7	-10.0
L	(-)				

* Optimal voltage may vary based on cable and torch configuration.



Connection Diagram







Sense Leads



An electrode sense lead is required. This is a standard connection in an $\mbox{Arclink}^{\mbox{${\rm @}$}}$ cable.



For best performance, connect the work sense lead close to the welding arc.





Connect the work lead to the work stud on the module and directly to the work piece. Maintain the shortest connection length possible.



For configurations with excessive inductance, use Lincoln Electric[®] patented coaxial welding cables.



A work sense lead (optional) is highly recommended for total welding cable lengths >50 ft. and should be connected directly to the workpiece.



The work sense lead should be separated away from welding cables to minimize interference.



DO NOT connect either sense lead to a welding stud as this may result in erratic arc or increased spatter.



DO <u>NOT</u> route sense lead cable close to high current welding cables as this may distort the sense lead signal.



The total length of the welding current loop (A+B+C) should be minimized to reduce inductance.



Lincoln Electric[®] coaxial cables combine the positive and negative welding leads into one cable to minimize cable inductance.

Route cables (A,B) close together to further reduce cable inductance.



Test cable inductance levels using the Power Wave[®] Manager software exclusively from Lincoln Electric[®].

Troubleshooting



The Performance You Need. The Quality You Expect.

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Troubleshooting



Check	00			V	≁ ?°
	Wire Feed Speed	UltimArc™	Travel Speed	Volts	Push Angle
Burnthrough					
Action					

Check	O Wire Feed Speed	UltimArc TM	Volts	Travel Speed	Push Angle
Under Cut			➡	♥	✿







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Increase

Decrease

Important

Inspect & Replace

Troubleshooting



NOTES: Aluminum is more susceptable to some issues which can be easily fixed with the right tools.

Arc Wandering - tends to be more prevalent with 5000 series wires. This can be minimized by introducing a Spring Loaded Tip which provides a constent contact point for the current path.

Soot - is undesirable from an appearance standpoint, but can not be completely eliminated. It is important to remember that black soot around the weld bead is acceptable. If soot is present on the weld bead the operator should verify all set-up and procedures. Voltage and gas coverage are two main culprints of this problem.

Erratic Arc Behavior - can be caused from various components in the weld system. It is important to clean gun liners, change contact tips, and check wire tension. Drive rolls should not be overtightened causing the wire to deform as it exits the feeder.

Torch Calibration - Some push pull systems require the operator to verify wire feed speed calibration. Following the torch manufacturers calibration recommendations can prevent major feeeding issues.



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		Material	OO Wire Feed		V	Α	т	Contact Tip to Work		
Wire Type	Gas	Thickness	Speed	Travel Speed	Volts	Amps	Trim	Distance	Arc Length	Control Knob
Weld Stud	Torch	Electrode Sense Lead	Work Sense Lead	Work Clamp	Torch Nozzle	Heat Input	Heat Input (Low)	Arc Focus	Arc Focus (Narrow)	UltimArc™
Stop / Avoid	Gap Bridging	Seuse Lead				(High)	(LOW)	(Broad)	(Nariow)	

Technical Terms

Soot A black substance which collects near or on the we	d bead.
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- **Burnthrough** _____ A hole in the base material caused by excessive heat input during welding.
- Cable Inductance Resistance to change in current.
- GMAW_ __Gas metal arc welding including metal inert gas (MIG) and metal active gas (MAG) welding.
- _____Gas entrapped in solidifying metal forms spherical or elongated pores in the weld. Porosity___
- Push Angle____ _____ The angle at which the electrode leads the weld pool relative to the direction of travel.
- A wire feed speed used to establish an arc. Run-In Speed
- _____ The angle of the electrode, off perpendicular, relative to the work piece surface. Work Angle_

Procedure Notes

All listed procedures are starting points and may The result of welding at higher travel speeds is a At faster travel speeds, the bead-shape can require some adjustment depending on the specific application.

mill scale, joint fit up, and joint consistency are factors that may require special consideration required. depending on the specific application.

At higher travel speeds, joint fit up, wire placement, and contamination all become factors that are more significant.

tendency to produce more spatter, less become very convex (or ropy), and the weld will not penetration, more undercut, and a less desirable "wet" well. There is a point at which the arc is set so bead shape. Depending on the limitations / short that the arc will become unstable and Torch angle, electrode placement, contamination, requirements of the actual application, slower stubbing will occur. This forms a limitation of just travel speeds and higher arc voltages may be how fast the travel speed can be raised.

> As the travel speed increases in fast follow applications (1/4" to 14 Gauge), a tighter and arc profile, and structural integrity of a given weld length must be maintained so that the puddle properly follows the arc. Operators typically reduce the arc length control (Trim) to achieve this.

It is ultimately the responsibility of the end user to ensure the proper weld deposition rate, bead application.

Customer Assistance Policy

The business of The Lincoln Electric Company is manufacturing and selling high quality welding equipment, consumables, and cutting equipment. Our challenge is to meet the needs of our customers and to exceed their expectations. On occasion, purchasers may ask Lincoln Electric for information or advice about their use of our products. Our employees respond to inquiries to the best of their ability based on information provided to them by the customers and the knowledge they may have concerning the application. Our employees, however, are not in a position to verify the information provided or to evaluate the engineering requirements for the particular weldment. Accordingly, Lincoln Electric does not warrant or guarantee or assume any liability with respect to such information or advice. Moreover, the provision of such information or advice does not create, expand, or alter any warranty on our products. Any express or implied warranty that might arise from the information or advice, including any implied warranty of merchantability or any warranty of fitness for any customers' particular purpose is specifically disclaimed.

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